

Form PTO-1449	ATTY DOCKET NO. SD-6851	APPLICATION NO. TBD
INFORMATION DISCLOSURE CITATION IN AN APPLICATION	APPLICANT Xavier, et al.	U.S. PTO 1027096
(Use several sheets if necessary)	FILING DATE 15/22/01	GROUP TBD

U.S. PATENT DOCUMENTS

FOREIGN PATENT DOCUMENTS

OTHER DOCUMENTS

Author (including name of the author (in CAPITAL LETTERS), title of the article (when appropriate), title of the item (book, magazine, journal, serial, symposium, catalog, etc.), date, page(s), volume-issue number(s), publisher, city and/or country where published).

RG		Otter et al., "Hybrid Modeling in Modelica based on the Synchronous Data Flow Principle," CACSD'99, August 22-26, Hawaii, USA, 1999, pp. 1-7.
RG		Mattsson et al., "An Overview of the Modeling Language Modelica," Eurosim'98 Simulation Congress, April 14-15, 1998, Helsinki, Finland, pp. 1-5.
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RG		Dixon et al., "RAVE: A Real and Virtual Environment for Multiple Mobile Robot Systems," Proceedings of the 1999 IEEE/RJS International Conference on Robotics and Systems (IROS '99), pp. 1-8.
RG		Diaz-Calderon et al., "A Composable Simulation Environment for Mechatronic Systems," 1999 SCS European Simulation Symposium, Erlangen, Germany, October 26-28, 1999, pp. 1-7.
RG		Stewart et al., "Design of Dynamically Reconfigurable Real-Time Software Using Port-Based Objects," IEEE Transactions on Software Engineering, Vol. 23, No. 12, December (1997), pp. 759-776

EXAMINER <i>R. Grill</i>	DATE CONSIDERED <i>6/12/2005</i>
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EXAMINER: Initial if citation considered, whether or not citation is in conformance with M.P.E.P. 609; Draw line through citation if not in conformance and not considered. Include copy of this form with next communication to patentee.

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EXAMINER INITIAL	DOCUMENT NUMBER	DATE	NAME	CLASS	SUB CLASS	FILING DATE IF APPROPRIATE

FOREIGN PATENT DOCUMENTS

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RG	Anderson, R. J., "Building A Modular Robot Control System Using a Passivity and Scattering Theory", 1996 IEEE International Conference on Robotics and Automation (ICRA), Minneapolis, MN 1996, pp 698-705.
RG	Hudson, et al, "V-Collide: Accelerated Collision Detection for VRML", Proceedings VRML '97, Monterey, CA February 1997.
RG	Kavraki and Latombe, "Chapter 3: Probabilistic Roadmaps for Robot Path Planning," in Practical Motion Planning in Robotics, Gupta, Kamal; DelPobil, Angel P. (ed.s) John Wiley & Sons, Chichester (West Sussex), England 1998, pp. 33-53
RG	Xavier, Patrick, "Fast Swept-Volume Distance for Robust Collision Detection", IEEE International Conference On Robotics and Automation, Albuquerque, NM, April 20-25, 1997
RG	Schoenwald et al, "Decentralized Control of a Collective of Autonomous Robotic Vehicles, 2001 American Control Conference, Arlington, VA June 25-27, 2001.

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Form PTO-1449 (SNL-Modified) (2-97)
List of Patents and Publications
for Applicant's Supplemental
Information Disclosure Statement

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Serial Number:

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(use several sheets if necessary) GROUP: 2123 FILING DATE: October 22, 2001

REFERENCE DESIGNATION

Ex'r Init	Document No. Date	Name	U.S. Patent Documents		Sub Class Class	File Date
			Foreign Patent Documents			
	Document No. Date	Name		Sub	Translation	

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RG IAD | 5,247,650 9/21/93 Judd et al.

OTHER ART (Including Author, Title, Date, Pertinent Pages, Etc.)

Examiner: R. Guelle

Date Considered: 6/12/2005

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